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On the Algebraic Geometry of Contact Formation Cells for Systems of Polygons A.O. Farahat P.F. Stiller Dept. of AE Dept. of Math aof4691@venus.tamu.edu stiller@alggeo.tamu.edu J.C. Trinkle Dept. of cs ftrink@cs.tamu.edu Texas A&M University, College Station, TX 77843 Abstract The efficient planning of contact tasks for intelligent robotic systems requires a thorough understanding of the kinematic ...

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